

Polarized Spaces of Polar Rank Three Which are Locally a Direct Product

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We present characterizations of geometries associated with buildings of type $C_{n,n-2}$, $D_{n,n-2}$ ($n \geq 4$), $E_{7,4}$, $E_{8,5}$.

1. DEFINITIONS AND NOTATIONS

An incidence system $\Gamma = (\mathcal{P}, \mathcal{L})$ is a set \mathcal{P} of points together with a family \mathcal{L} of distinguished subsets of \mathcal{P} of cardinality at least 2, called lines. Two points p and q are said to be collinear if they are on a common line (denoted by $p \perp q$).

The incidence system Γ is said to be (partial) linear if any two distinct points are on at most one line. If p and q are two collinear, distinct points of a linear incidence system, then pq stands for the unique line through p and q .

The collinearity graph of Γ is the graph the vertices of which are the points of Γ and the edges of which are the pairs of distinct collinear points. Terms such as connectedness, path and distance will be used in Γ when they are meant for the collinearity graph. For points p and q , $d(p, q)$ denotes the distance between p and q . Further, p^\perp stands for the set of all points collinear with p . If X is a set of points, then $X^\perp = \bigcap_{p \in X} p^\perp$.

A subspace X of Γ is a subset of \mathcal{P} such that every line intersecting X in two distinct points is completely contained in X . A subspace is singular if all its points are pairwise collinear. A singular subspace is called maximal if it is not properly contained in another singular subspace. The length i of a longest chain $X_0 \subsetneq X_1 \subsetneq \cdots \subsetneq X_i = X$ of singular subspaces X_j of a singular subspace X is called the rank of X . A maximal singular subspace of rank at least 2 will be called a max space for short.

A geodesic is a path joining p to q , the length of which is equal to the distance $d(p, q)$. A set of points X is called geodesically closed or convex if for every pair of points p and q of X , every geodesic joining p to q is contained in X . Now it is clear that the intersection of geodesically closed sets is again geodesically closed. Moreover, any intersection of geodesically closed subspaces is also a geodesically closed subspace. This allows us to talk about the geodesical closure of a set of points X , denoted by $\langle X \rangle$.

We recall from [5] that Γ is a polar space of finite rank r if the following conditions are satisfied: (i) for every point p and every line L , p is collinear with either one or all points of L ; (ii) no point of Γ is collinear with all other points; (iii) every singular subspace has rank at most r , and there is such a singular subspace of rank r .

A polar space of rank 2 is also called a generalized quadrangle.

The results of Buekenhout and Shult [5], Tits [12] and Veldkamp [14] classify all polar spaces of rank r at least 3, and having lines containing at least three points: these are exactly the point–line geometries $C_{r,1}$ and $D_{r,1}$ associated to the buildings of type C_r and D_r . Polar spaces of type $D_{r,1}$ will be called lean polar spaces, and polar spaces not of this type will be called fat polar spaces.

We will say that Γ is a polarized space of polar rank $r+1 \geq 3$ if the following conditions hold:

- (1) If L is a line and p is a point collinear with at least two distinct points of L , then p is collinear with all points of L .

(2) If p and q are non-collinear points with $|p^\perp \cap q^\perp| \geq 2$, then $p^\perp \cap q^\perp$ is a polar space of rank r .

(3) (i) The structure is connected but is not complete; (ii) every line contains at least three points; (iii) the set $p^\perp - \{p\}$ is connected for every point p ; (iv) the maximal singular subspaces have finite rank.

We will mainly consider polarized spaces of polar rank 3.

Two points p and q at distance 2 form a polar pair or a special pair according to whether or not the condition of axiom 2 holds.

The geodesic closure of a polar pair is isomorphic to a polar space [4] and is called a hyperline or a symplectum.

Let p be a point of Γ . The residue of Γ at p , denoted by Γ_p , is the incidence system $(\mathcal{P}_p, \mathcal{L}_p)$ defined as follows: \mathcal{P}_p is the set of all lines of Γ on p ; the set of all lines on p contained in a plane (singular subspace of rank 3) of Γ on p is an element of \mathcal{L}_p . If A is an incidence system isomorphic to Γ_p for all points p , then Γ is said to be locally A . Remark that axiom 3(iii) states that Γ_p is connected for every point p . We will say that Γ is locally connected for every point p .

Two lines L and M are called coplanar if they are contained in some plane. Then every point of L is collinear with every point of M , and so we write $L \perp M$. We remark that this notation keeps its right meaning in Γ_p , if we use \perp as collinearity in Γ_p as well.

If X_p is a subset of Γ_p , then the union of all lines in X_p is denoted by $\cup X_p$. Hence $\cup X_p$ is a subset of the point set of Γ .

We recall a result from [4].

PROPOSITION *If Γ is a polarized space of polar rank 3, then for every point p the following properties hold in Γ_p :*

- (i) *two distinct collinear points are contained in exactly one line;*
- (ii) *two points at distance 2 are contained in a geodesically closed subspace which, together with its lines, is a generalized quadrangle (these generalized quadrangles will be called quads—a quad which is not a grid is said to be fat);*
- (iii) *the structure is not complete and is connected.*

For definitions such as diagram, geometry, truncation, etc. we refer to [2].

2. CHARACTERIZATION OF $C_{n,n-2}$

Suppose that each line X of the polarized space Γ is contained in a hyperline of type C_3 and a max space, partitioning the set of planes on X . Then Γ is the geometry of points and lines corresponding to a thick building of type $C_{n,n-2}$ for $n \geq 4$ or a quotient of it.

PROOF. First consider the residue Γ_p at a point p : it will be connected in view of axiom 3(i). By supposition there is on each point x of Γ_p exactly one fat quad and one maximal singular space of rank at least 2, such that they form a partition of all lines through x .

In Γ_p we can distinguish between two kinds of lines; (i) lines contained in a fat quad, and (ii) lines not contained in any fat quad.

We will call the latter special lines, and the maximal singular spaces having no line in common with a fat quad are special spaces. It is clear that there is exactly one special space on a given special line.

We will prove that Γ_p can be identified with the direct product of a projective space and a fat generalized quadrangle (at least three lines on a point), and hence is of type $A_i \times C_2$.

It should be clear that two fat quads are necessarily disjoint, and the same can be said about the special spaces. From the proof of Lemma 3.5 in [10] we take over the following property: every point not contained in a given fat quad, H , is collinear with exactly one point of H . In particular, it follows that each special space R and each fat quad H meet in one point: for suppose that $R \cap H = \emptyset$, then we can choose points r in R and x in H such that $r \perp x$. The line rx is not contained in the fat quad H on x , so must be special. But then $rx \subset R$ because there is only one special space on r . This gives us $x \in R \cap H$, contradicting our assumption. On the other hand, suppose x and y would be two distinct points of R and H . Then R and H would have the line xy in common, again a contradiction.

Consider now two fat quads, H and H' . For a point x of H , we define $\sigma(x) = x'$ as the unique meeting point of H' and the special space on x . Clearly σ is a map, and interchanging the roles of H and H' we see that σ is a bijection from H to H' . We show that σ is an isomorphism. consider therefore two collinear points x and y of H ; put $x' = \sigma(x)$ and $y' = \sigma(y)$. Let Q be the grid on x, y and x' ; then Q has x' in common with H . This means that $Q \cap H'$ is a line L of H' , so there exists a point y'' (on L) collinear with y . But y is collinear with only one point of H' , so $y'' = y'$. In particular, $y' \perp x'$, so σ is an isomorphism.

Next consider two special spaces, R and R' . For a point x of R , we define $\tau(x) = x'$ as the unique meeting point of R' and the fat quad on x . As before, τ is a bijection. We prove that τ maps lines of R onto lines of R' . Let L be any line of R , and choose a point x on L . Suppose first that $\tau(x)$ is collinear with x . Call Q the grid containing L and x' ; then Q has a line L' in common with R . If y is a point of L , then $\tau(y)$ will be a point of L' . So far τ maps lines onto lines. Suppose now that $\tau(x)$ is at distance 2 of x . Choose $x'' \in \tau(x)^\perp \cap x^\perp$, and let R'' be the special space on x'' . By the first part we can define an isomorphism τ' from R to R'' , and an isomorphism τ'' from R'' to R' . So $\tau = \tau'' \tau'$ is also an isomorphism.

We conclude that Γ_p can be identified with the direct product of a projective space and a (fat) generalized quadrangle as follows. For any special space R and fat quad H define the canonical map:

$$\rho: \Gamma_p \rightarrow R \times H, \quad x \rightarrow (\tau(x), \sigma(x)).$$

Going back to Γ , we make the following observations: every line of Γ is contained in exactly one special space. If two lines meet in a point p , then our knowledge about Γ_p tells us that the corresponding special spaces are isomorphic; in particular, they have the same dimension. In view of the connectedness of Γ , this is so for all special spaces of Γ . An analogous reasoning leads us to say that all fat hyperlines of Γ are isomorphic. We may take $\Gamma_p \cong A_i(K) \times C_2(K)$ independent of the point p . In particular, the dimension of the special spaces of Γ is then $i + 1$.

In view of the results in [40], every special space and fat hyperline of Γ meeting in a line determine a convex subgeometry of type $A_{1+2,2}$. We denote the set of all these Grassmannians by Γ_0 , the set of all special spaces by Γ_1 , $\Gamma_2 = \mathcal{P}$, and the set of all fat hyperlines by Γ_3 . We also define an incidence between these objects as follows:

- (i) an object of type 0 (resp., 1) is incident with one of type 3 if they intersect in plane (resp., line);
- (ii) inclusion for all remaining cases.

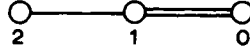
We observe the following properties in Γ :

- (i) every line is contained in exactly one special space;
- (ii) every plane of a fat hyperline is contained in exactly one member of Γ_0 . (Consider an arbitrary line in this plane α ; then it is contained in the special space R . Both R and α determine a unique member of Γ_0 .)

If we take $1 + 3 = n$, then we claim that we defined a geometry of $\{4, \dots, n\}$ -truncated type C_n . For this we look first at the residue of a point p (object of type 2): we have the geometry of all Grassmannians, special spaces and fat hyperlines containing p . Otherwise stated, the geometry of direct products of type $A_i \times A_1$, special spaces (type A_i) and fat quads (type C_2) of the residue $\Gamma_p \cong A_i \times C_2$. This gives us a truncated geometry of type:



On the other hand, we consider the residue of an object of type 3 (a fat hyperline), say H . In view of the properties (i) and (ii) stated above we can identify this geometry with the geometry of planes, lines and points lying in H . Therefore that is a diagram of type:



From this, the residual connectedness also follows, proving our claim.

Now we can apply Theorem 2 from [2]: Γ is a $\{4, \dots, n\}$ -truncated geometry Δ/A , with Δ a building of type C_n and A a group of automorphisms of Δ . Since every line is contained in one special space and one fat hyperline, the lines of Γ can be identified with the 2-shadow of flags of type $\{1, 3\}$. Renumbering the nodes as usual we conclude that Γ is the geometry of points and lines of a building of type $C_{n,n-2}$ ($n \geq 4$) or a quotient of it.

3. POLARIZED SPACES THAT ARE LOCALLY A DIRECT PRODUCT

In this section we are considering a polarized space such that through every line of it go exactly three max spaces. We start with the study of the residue Γ_p which is connected in view of axiom (3) (i). Further, every point x of Γ_p is contained in exactly three max spaces, and all quads on x are grids. We introduce the following notation for the unique member v of $a^\perp \cap b^\perp - \{u\}$ (for $u \in a^\perp \cap b^\perp$): $v = a + b - u$.

LEMMA 3.1. *Let X and x' be two collinear but distinct points of Γ_p . Let a and b be two points collinear with x but not with x' , $a' = x' + a - x$, $b' = x' + b - x$. Then $a \perp b$ iff $a' \perp b'$.*

PROOF. Suppose first that a, b and x are on the same line; then the grid on x, x' and a contains b , and also the line a'/x' . This line goes through b' , so this case is settled.

Next, assume that a and b are collinear, but the line ab does not contain the point x . In order to derive a contradiction suppose that a' and b' are not collinear. Call the max space through the line $x'b'$, R' . We show that we can assume that a is collinear with a point of R' . Suppose the contrary. The point b' is contained in three max spaces,

namely one through the line bb' , R' and a third, say, R'' . Then the point $a'' = a + b' - b$ must belong to R'' . Consider a point c on the line ax , distinct from a and x . If R' has a point c' collinear with c , then we interchange the roles of a and x (and derive a contradiction, as will be proved later on). So assume again that $c'' = c + b' - b$ belongs to R'' , then $a'' \perp c''$. If Q is the grid on a, c, c'' and a'' (If $c \perp a''$ then $x \perp a''$ and so $a'' = x'$, a contradiction) then Q contains the line $ca = ax$, and hence $x^\perp \cap R'' \neq \emptyset$. But this is impossible because $x^\perp \cap b'^\perp = \{b, x'\}$. Hence a is collinear with a point y of R' . This implies that $a^\perp \cap x'^\perp$ would contain three distinct points a', y and x , another contradiction. We conclude that a' and b' are collinear.

On the other hand, as $a = x' + a' - x$ and $b = x' + b - x$ we can apply the first part of this proof again to show the converse. \square

LEMMA 3.2. *The residue Γ_p can be identified with the direct product of three projective spaces, and so is of type $A_i \times A_j \times A_k$.*

PROOF. The first remark that there is one max space on every line of Γ_p . We prove now that two max spaces R_1 and R_2 meeting in a point x , are contained in just one convex subgeometry of Γ_p that can be identified with $R_1 \times R_2$.

Consider a point a_1 (resp., a_2) distinct of x in R_1 (resp., R_2). Write

$$\begin{aligned}\theta(a_1, a_2) &= a_1 + a_2 - x, & \theta(a_1, x) &= a_1, \\ \theta(x, a_2) &= a_2, & \theta(x, x) &= x, \\ D &= \{\theta(a_1, a_2) \mid a_1 \in R_1, a_2 \in R_2\}.\end{aligned}$$

The set D is a subset of the convex hull of R_1 and R_2 . We claim that the map θ is an isomorphism:

$$\begin{aligned}\theta: R_1 \times R_2 &\rightarrow D \\ (a_1, a_2) &\rightarrow \theta(a_1, a_2).\end{aligned}$$

Because $x^\perp \cap \theta(a_1, a_2) = \{a_1, a_2\}$, it follows from $\theta(a_1, a_2) = \theta(b_1, b_2)$ that $a_1 = b_1$ and $a_2 = b_2$. So θ is a bijection. We show that θ^{-1} is an isomorphism.

Consider therefore a point b_1 in $R_1 - a_1x$ and b_2 in $R_2 - a_2x$. Then we prove that $\theta(a_1, a_2)$ and $\theta(b_1, b_2)$ are not collinear by deriving a contradiction. Thus we assume that $\theta(a_1, a_2)$ and $\theta(b_1, b_2)$ are collinear. From the foregoing lemma it follows that $\theta(a_1, b_2)$ is collinear with $\theta(a_1, a_2)$ and with $\theta(b_1, b_2)$. If these three distinct points are on the same line, then $b_2 \perp \theta(b_1, b_2)$ and $b_2 \perp \theta(a_1, b_2)$ implies $b_2 \perp \theta(a_1, a_2)$ by axiom (1). But then $b_2 = a_2$. So these three points should not be one the same line. Now $a_1, \theta(b_1, b_2)$ belongs to $\theta(a_1, b_2)^\perp \cap \theta(a_1, a_2)^\perp$, so they are collinear. This means that $a_1 = b_1$, a final contradiction.

From this we derive that if $\theta(a_1, a_2) \perp \theta(b_1, b_2)$, then $a_1 = b_1$ or $a_2 = b_2$. Suppose we are in the first case, with a_1, a_2, b_2 distinct from x . Let L be the line joining $\theta(a_1, a_2)$ and $\theta(a_1, b_2)$. For an arbitrary point c of the line a_2b_2 , $\theta(a_1, c)$ belongs to L (indeed, the grid on b_2 and $\theta(a_1, a_2)$ contains a_2 and $\theta(a_1, b_2)$ and hence also the lines a_2b_2 and L . Therefore $\theta(a_1, c)$ is the unique point in $c^\perp \cap L$). An analogous reasoning holds for the latter case in which $a_2 = b_2$.

Now consider two distinct points a_1, b_1 in R_1 (take $b_1 \neq x$) and a point b_2 in R_2 distinct from x . Since $x^\perp \cap \theta(b_1, b_2)^\perp = \{b_1, b_2\}$, $a_1 \not\perp \theta(b_1, b_2)$. It is also clear that $b_1 \not\perp b_2$. All this leads to the fact that the set D is a subspace of Γ_p and θ is an isomorphism. Hence the diameter of D is 2, and D is also 2-convex.

We describe D somewhat further: the max spaces contained in D split up into two families, \mathbb{R}_1 and \mathbb{R}_2 . Each family is a partition of D . If $R_1 \in \mathbb{R}_1$ and $R_2 \in \mathbb{R}_2$ then we

note that $D = R_1 * R_2$, and 'par abus de langage' talk about the direct product of R_1 and R_2 .

Let R_3 be the third max space on x . If X_k is an arbitrary point of R_3 , then we can define $D_k = R_1^k * R_2^k$, with R_1^k and R_2^k the two remaining max spaces on x distinct from R_3 .

We prove that D_i and D_j are disjoint for $i \neq j$. To derive a contradiction, suppose y belongs to D_i and D_j . If $d(y, R_3) = 1$, say $x' \in y^\perp \cap R_3$, then $y \perp x_i$ and $y \perp x_j$. (For $d(y, x_i) = 2$ would imply that x' belongs to D_i and D_j .) If $d(y, R_3) = 2$, take $x_i^\perp \cap y^\perp = \{a_1, a_2\}$ and $x_j^\perp \cap y^\perp = \{b_1, b_2\}$. In view of axiom (4) we can assume, without loss of generality, that $a_1 \perp b_1$. So a_1, b_1, x_j, x_i form a quadrangle having a_1 and x_1 in common with the quadrangle a_1, y, a_2, x_i . As $b_1 \perp y$, we have $a_2 \perp x_j$ if we apply Lemma 3.1 on x_j and a_1 . Since a_2 is collinear with two distinct points x_i and x_j of R_3 , it must belong to R_3 . But then $d(y, R_3) = 1$, which is impossible.

Next we show that for any point z of $\Gamma_p - D$, $z^\perp \cap D$ contains exactly one point. In view of the connectedness of Γ_p , there is a point d of D at shortest distance of z . We have to prove that $d(z, d) = 1$. So suppose that $d = z_0, a_1, z_2, \dots, z_n = z$ is a geodesic path from d to z , $n \geq 2$. In particular, $z_0 \not\perp z_2$, so we have grid on z_0 and z_2 . This grid has a line L in common with D , for there are only three max spaces on z_0 . But then $z_2^\perp \cap L \neq \emptyset$, and *a fortiori* $z_2^\perp \cap D \neq \emptyset$, a contradiction. We conclude that $d(z, D) \leq 1$. On the other hand, suppose that $d_1, d_2 \in z^\perp \cap D$ are two distinct points; then we can consider two cases. First, d_1 and d_2 are collinear. The line $d_1 d_2$ belongs to D , and in particular z is a point of D for D contains also the max space on $d_1 d_2$. Second, d_1 and d_2 are not collinear, but then $z \in d_1^\perp \cap d_2^\perp$ is again a point of D , for D is convex. The point $d \in z^\perp \cap D$ is unique. If $z \in D$, we take $z = d$. We define a map σ as follows: $\sigma(z) = d$.

We now show that for any point z of Γ_p , $d(z, R_3) \leq 2$. For this, let z be a point of Γ_p with $d(z, R_3) \geq 2$. From the foregoing sections follows the existence of a point $d \in z^\perp \cap D$. Of course, $d \not\perp x$ by assumption, so take $x^\perp \cap d^\perp = \{a, b\}$. Define $c = z + a - d$ and $x' = c + x - a$. We claim that x' belongs to R_3 . Suppose the contrary: then xx' , xa and xb are three lines on x of which no two are contained in the same projective space. Together with R_3 , there would be at least four distinct max spaces on x . This contradiction proves our claim.

Next we prove that there is exactly one subspace D_k on any given point z of Γ_p . In view of what we have already proved, it suffices to show that there is at least one on a given point z . First, suppose that $d(z, R_3) = 2$, and choose x_k in R_3 such that $d(z, x_k) = 2$. The points z and x_k are contained in a unique quad Q_k . Of course, this quad has no lines in common with R_3 for $d(z, R_3) = 2$. Both lines on x_k of Q_k are thus in D_k . In particular, $Q_k \subset D_k$, and so $x_k \in D_k$. Secondly, suppose $d(z, R_3) = 1$, then choose $x_k \in z^\perp \cap R_3$, and clearly D_k will contain z . Finally, if $z \in R_3$, then take $z = x_k$. With the notations introduced here, we define a map τ as $\tau(z) = x_k$.

As a last step in this proof, we define the following canonical map:

$$\rho: \Gamma_p \rightarrow R_3 \times D, \quad z \rightarrow (\tau(z), \sigma(z)).$$

We will prove that ρ is an isomorphism.

First of all, ρ is a bijection: for a point x of R_3 and a point d of D , we construct a point z of Γ_p for which $\tau(z) = x$ and $\sigma(z) = d$. So consider the subspace D_k on x . In the very same way as before, we can show that $d^\perp \cap D_k$ contains exactly one point z . For this z clearly $\tau(z) = x$ and $\sigma(z) = d$ for $z \perp d$.

We make the following observations for an arbitrary point z of Γ_p . If D_k is the subspace on z described above, there is exactly one max space $R(z)$ on z , not contained in D_k . It should be clear by now that $R(z)$ meets every D_k in one point, and

that the set of all such max spaces (in particular R_3) constitute a partition of Γ_p . Let L be any line of Γ_p , and y a point of L . Then there are two (non-trivial) cases that can occur.

(1) L is in a subspace D_k ($\neq D$) on y . Let z be any point distinct from y on L . Through z and $\sigma(y)$ goes a quad Q . This quad meets D in a line L' on $\sigma(y)$. There is a point z' on L' collinear with z . Since $z' \in D$ and only one point of D is collinear with z (if $z \notin D$), we have $z' = \sigma(z)$. Hence,

$$\{\sigma(z) \mid z \in L\} = L'$$

is a line of D , so $\rho(L) = \{\tau(y)\} \times L'$.

(2) L is a max space $R(y)$ ($\neq R_3$) on y ; choose a point $z(\neq y)$ on L . If $y \perp \tau(y)$, consider the quad on z and $\tau(y)$. It meets R_3 in a line L' on $\tau(y)$. Call z' the point of L' collinear with z ; then $z' = \tau(z)$. In this case we also have

$$\{\tau(z) \mid z \in L\} = L',$$

so $\rho(L) = L' \times \{\sigma(y)\}$. If, on the contrary, $y \not\perp \tau(y)$, choose $a \in y^\perp \cap \tau(y)^\perp$. The quad on a and z has a line L' on a in common with $R(a)$. Let $z' \in z^\perp \cap L'$. The quad on $\tau(y)$ and z' meets R_3 in a line L'' on $\tau(y)$, so we can take $z'' \in z'^\perp \cap L''$. It is easy to see that if $d(z, R_3) = 2$, then $d(y, R_3) = 2$: $z \in R_3$ is excluded at once for, otherwise, $d(y, R_3) = 1$, and $d(z, R_3) = 1$ implies $y \perp \tau(z)$ (interchange the roles of y and z in the first part of this case), a contradiction. But z'' is a point of R_3 at distance 2 of z , so $z'' = \tau(z)$. In particular there holds

$$\{\tau(z) \mid z \in L\} = L'',$$

for when z runs through the line L , then z' will run through L' and hence z'' through L'' by applying the first part of this second case. The constructed L'' is therefore independent of z and hence $\rho(L) = L'' \times \{\sigma(y)\}$.

All this together shows us that ρ is an isomorphism. Both parts of this proof lead us to the conclusion that

$$\pi: \Gamma_p \rightarrow R_1 \times R_2 \times R_3$$

$$z \rightarrow (z_1, z_2, \tau(z))$$

with

$$\sigma(z) = \theta(z_1, z_2)$$

is an isomorphism. The lemma follows. \square

COROLLARY 3.3. *Suppose that there are exactly three max spaces on each line of the polarized space Γ , then Γ is locally $A_i \times A_j \times A_k$.*

PROOF. It suffices, in view of the theorem just proved, to show that the dimensions i, j, k are independent of the choice of the point p . Since Γ is connected, we can restrict our discussion to the case of two collinear points p and q . In Γ_p the line pq is a point, so there are three max spaces on pq of dimensions i, j and k . In Γ this means that the line pq is contained in three max spaces of dimensions $i+1, j+1$ and $k+1$. Back in Γ_q , pq is a point contained in three max spaces of dimensions i, j and k in Γ_q . \square

4. CHARACTERIZATION OF $E_{7,4}$ AND $E_{8,5}$

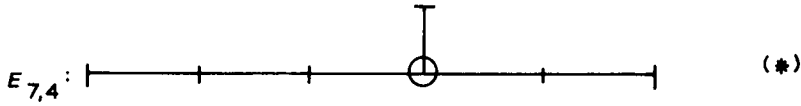
Suppose that every line X of the polarized space Γ is contained in exactly one maximal plane, one maximal 3-space and one 4-space (resp., 5-space). Then Γ is the geometry of points and lines of a building of type $E_{7,4}$ (resp., $E_{8,5}$), or a quotient of it.

PROOF. Just as in the foregoing theorem we can apply the results from []. There follows the existence of the following objects:

- (i) Convex subspaces isomorphic to a Grassmannian $E_{4,2}$, containing maximal planes and maximal 3-spaces. We call this set Γ_1 .
 - (ii) Convex subspaces isomorphic to a Grassmannian $A_{5,2}$, containing maximal planes and 4-spaces. We call this set Γ_2 .
 - (iii) Subspaces isomorphic to a Grassmannian $A_{6,3}$, containing maximal 3-spaces and 4-spaces. We call this set Γ_3 .
- Conversely, given a maximal plane (resp., 3-space, 4-space) and a maximal 3-space (resp., 4-space, plane) intersecting in a line then there is a unique member of Γ_1 (resp., Γ_3 , Γ_2) containing both.

Moreover, take $\Gamma_0 = \mathcal{P}$ and define the following incidence: (i) a point is incident with a Grassmannian (i.e. a member of Γ_1 , Γ_2 or Γ_3) if it lies in it; (ii) two Grassmannians are incident if they meet in a maximal singular subspace.

We now check that we have the following truncated diagram:



Remark first that on every maximal plane of Γ there is exactly one member of Γ_1 and one of Γ_2 . Analogously, there is unique member of Γ_2 and one of Γ_3 (resp. Γ_1) on every maximal 3-space of Γ . Consider now a 1-variety G_1 then the residual geometry of G_1 consists of the set of all points of G_1 , all 2-varieties meeting G_1 in a maximal plane and all 3-varieties meeting G_1 in a maximal 3-space. In view of both remarks made above, we can identify this geometry with the points of G_1 , the maximal planes and maximal 3-spaces lying in G_1 . Incidence between a maximal plane and a maximal 3-space becomes meeting in a line of G_1 . Therefore we obtain a truncated geometry of type $A_{4,2}$.

In particular it follows that the residues of flags of rank 2 containing a 1-variety are truncated geometries of the type as predicted by the truncated diagram (*). Moreover, these residues are residual connected. In the same way we can examine a 2-variety G_2 , checking with this all remaining conditions needed to apply Theorem 4 of [2]. It is easily verified that the lines correspond to the flags of type $\{1, 2, 3\}$ and conversely.

Taking account of the varieties we called points, we have that Γ is a truncated geometry of type $E_{7,4}$. In the same way one can prove the analogous statement for $E_{8,5}$. The theorem follows. \square

5. CHARACTERIZATION OF $D_{n,n-2}$ ($n \geq 5$)

Suppose that every line X of the polarized space Γ is contained in exactly two maximal planes and one $(j+1)$ -space ($j+1 \geq 3$). Then Γ is the geometry of points and lines of a building of type $D_{n,n-2}$ for $n \geq 5$, or a quotient of it.

PROOF. It follows from Corollary 3.3 that Γ is locally $A_1 \times A_1 \times A_j$. Hence, Γ satisfies the conditions described in 2, [10]. So there exists a set Γ_0 of convex subspaces of Γ , such that the following properties hold: (i) each member of Γ_0 is isomorphic to a Grassmannian $A_{j+2,2}$; (ii) every maximal plane and $(j+1)$ -space meeting in a line generate a member of Γ_0 .

We also define the following sets: Γ_1 is the set of all $(j+1)$ -spaces; $\Gamma_2 = \mathcal{P}$. Γ_3 is the set of all hyperlines not contained in a member of Γ_0 , and the corresponding incidence: (i)

an object of type 0 (resp. type 1) and one of type 3 are incident if they meet in a plane (resp. a line); (ii) inclusion for all remaining cases.

In the same way as in the proof of Theorem, one can check that this defines a $\{4, \dots, n\}$ -truncated geometry Δ/A , with Δ a building of type C_n and A a group of automorphisms of Δ ($n = j + 3 \geq 5$).

We remark that every 1-variety is contained in two 0-varieties. Then, by [12], Δ can also be seen as a building of type D_n . Hence, Γ is the geometry of points and lines of a building of type $D_{n,n-2}$ for $n \geq 5$, or a quotient of it by a group of automorphisms (not necessarily preserving the types n and $n - 1$). \square

6. CHARACTERIZATION OF $D_{4,2}$

Suppose that every line X of the polarized space Γ is contained in exactly three planes. Then Γ is the geometry of points and lines of a building of type $D_{4,2}$.

PROOF. By Lemma 3.2, Γ is locally $A_1 \times A_1 \times A_1$. Furthermore, every line is contained in exactly three lean hyperlines of rank 3. Now take: $\Gamma_1 = \mathcal{P}$; $\Gamma_2 = \mathcal{L}$; Γ_3 is the set of all planes of Γ ; Γ_4 is the set of all hyperlines of Γ ; together with inclusion as an incidence relation. Then we obtain a metasymplectic space where every line is contained in three hyperlines. By Tits [12], it follows that we may consider Γ as the geometry of points and lines of a building of type $D_{4,2}$ (because this geometry has diameter 3, quotients cannot occur). \square

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